

# Challenges in Avoiding Process Anomalies in Critical Infrastructure

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# Question

To what extent, and how, can we avoid anomalies in operational critical infrastructure?

# Tour Guide

A. Context

B. Anomalies

C. Detection



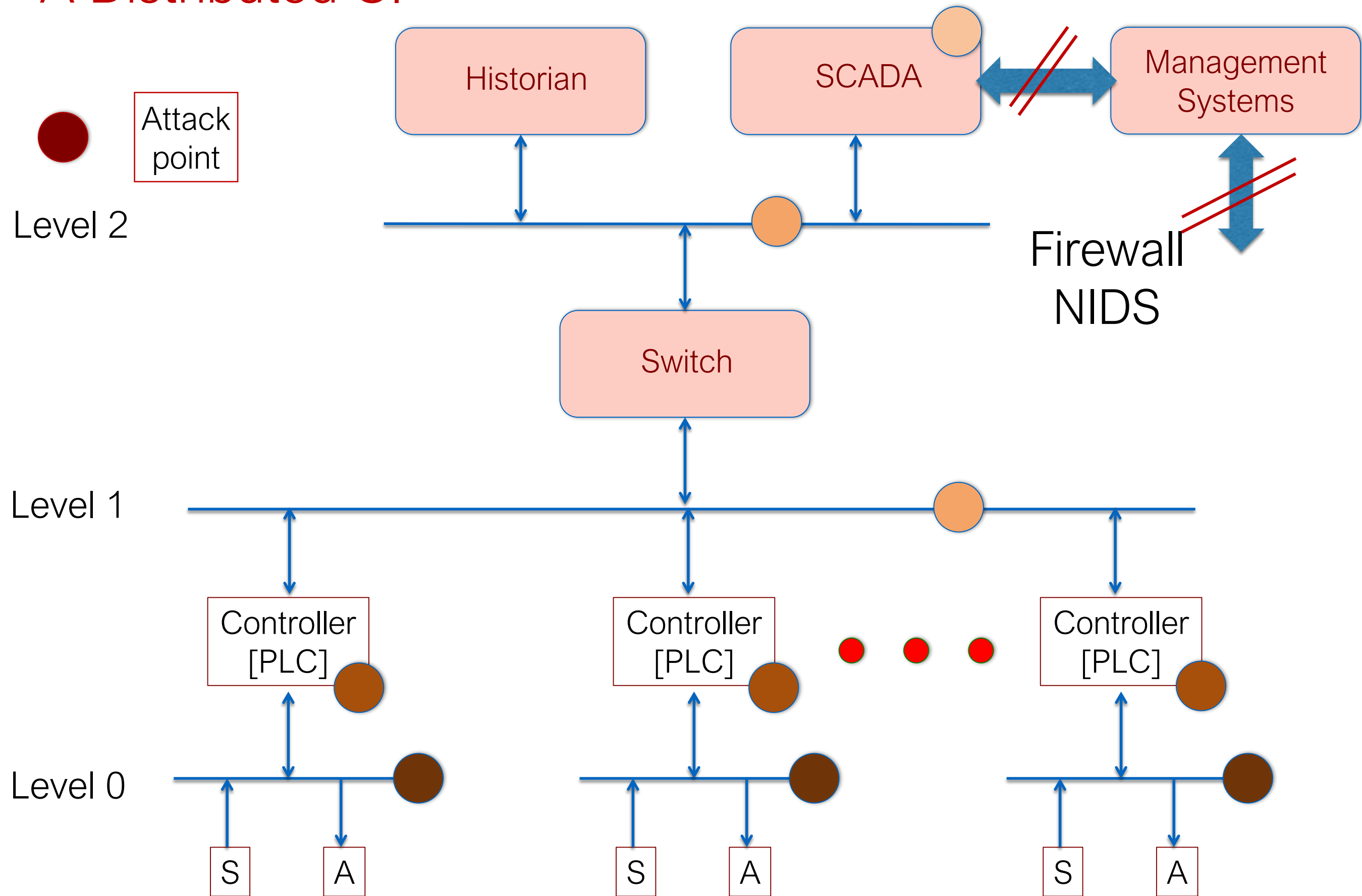
D. Command Validation

E. Experimental Evaluation

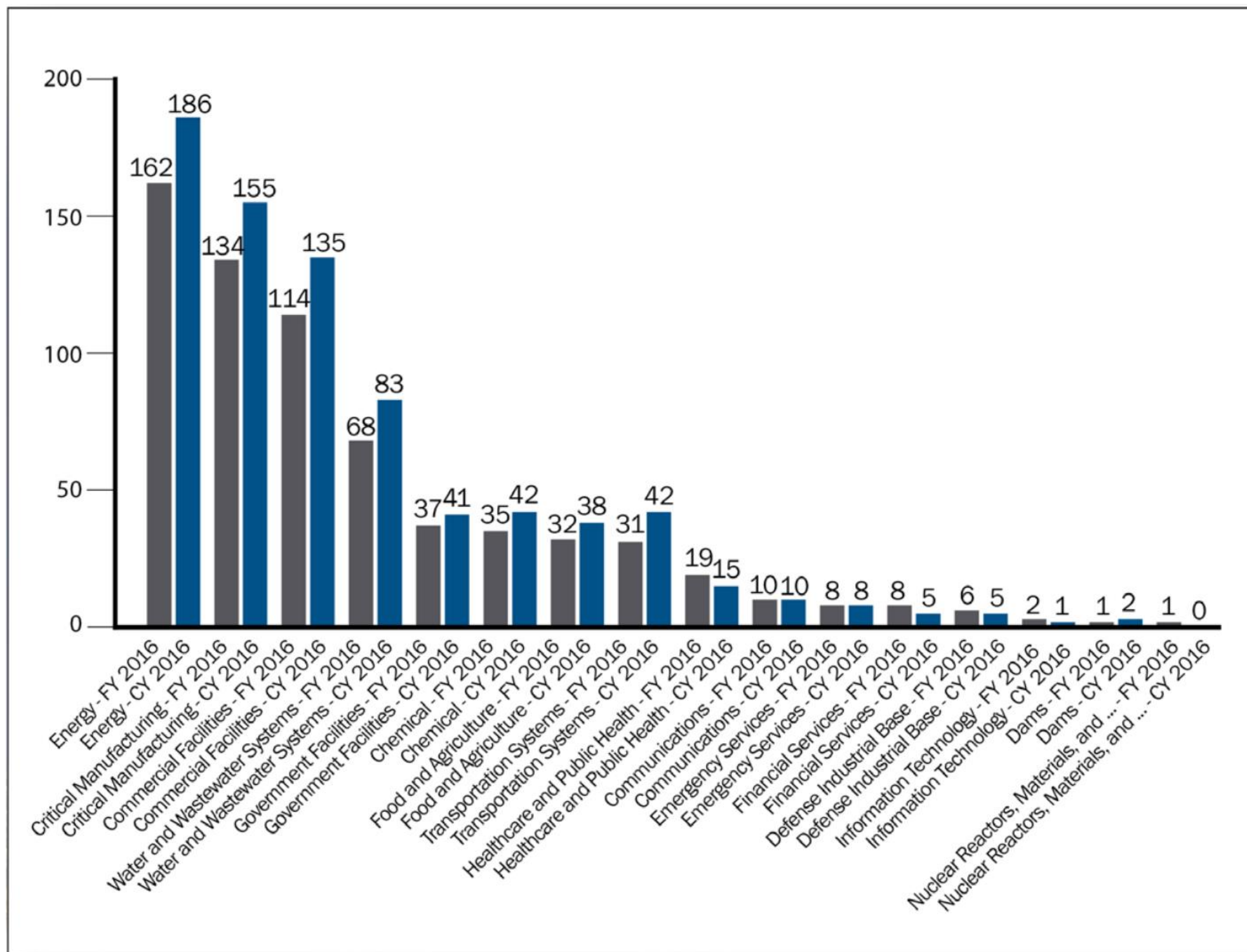
F. Next Steps

## A. Context

# A Distributed CI



# ICS-CERT Annual Vulnerability Coordination Report 2016



# Tools for Invasion

Ransomware

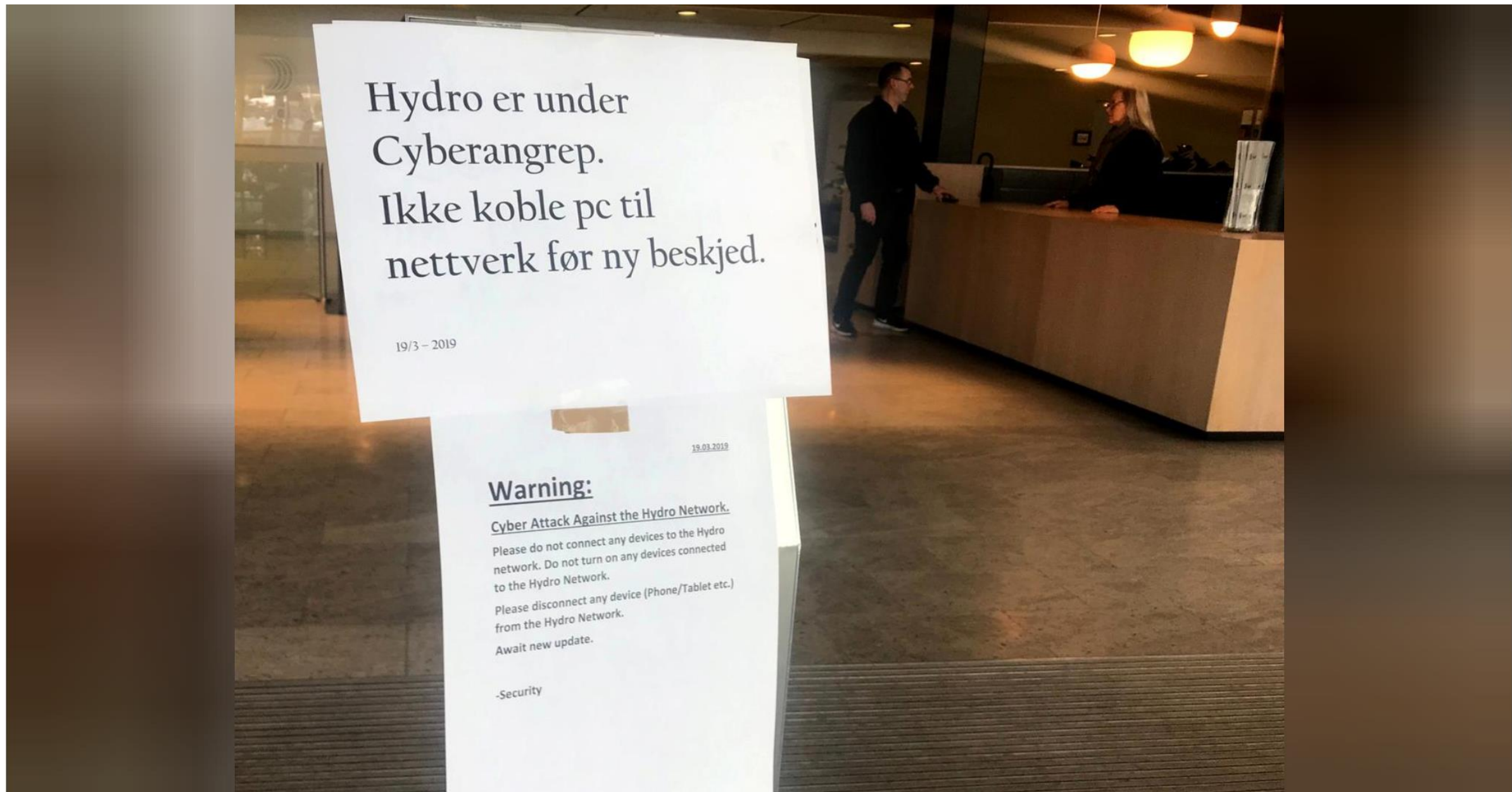
Malware

Virus





# A Recent Successful Attack: 2019 Norsk Hydro





# Critical Infrastructure: Interconnection

Water Treatment

Water Distribution



Electric power generation, transmission, distribution, AMI



## B. Anomalies

# Process anomaly

$q_i$  : plant state at time  $t=i$

Valid state sequence:

$$q_{-k} q_{-k+1} q_{-k+2} \dots q_{-1} q_0 q_1 q_2 \dots$$

Anomalous state sequence:

$$q_{-k} q_{-k+1} q_{-k+2} \dots q_{-1} \underbrace{q'_0 q'_1 q'_2 \dots}$$

Anomalous sequence

Question:

How to detect anomaly as close to  $q'_0$  as possible?

# Anomalies: Cause and Avoidance

Component failure

Communications failure

Programming errors

Process data manipulated

Actuator command manipulated

Fault tolerant design

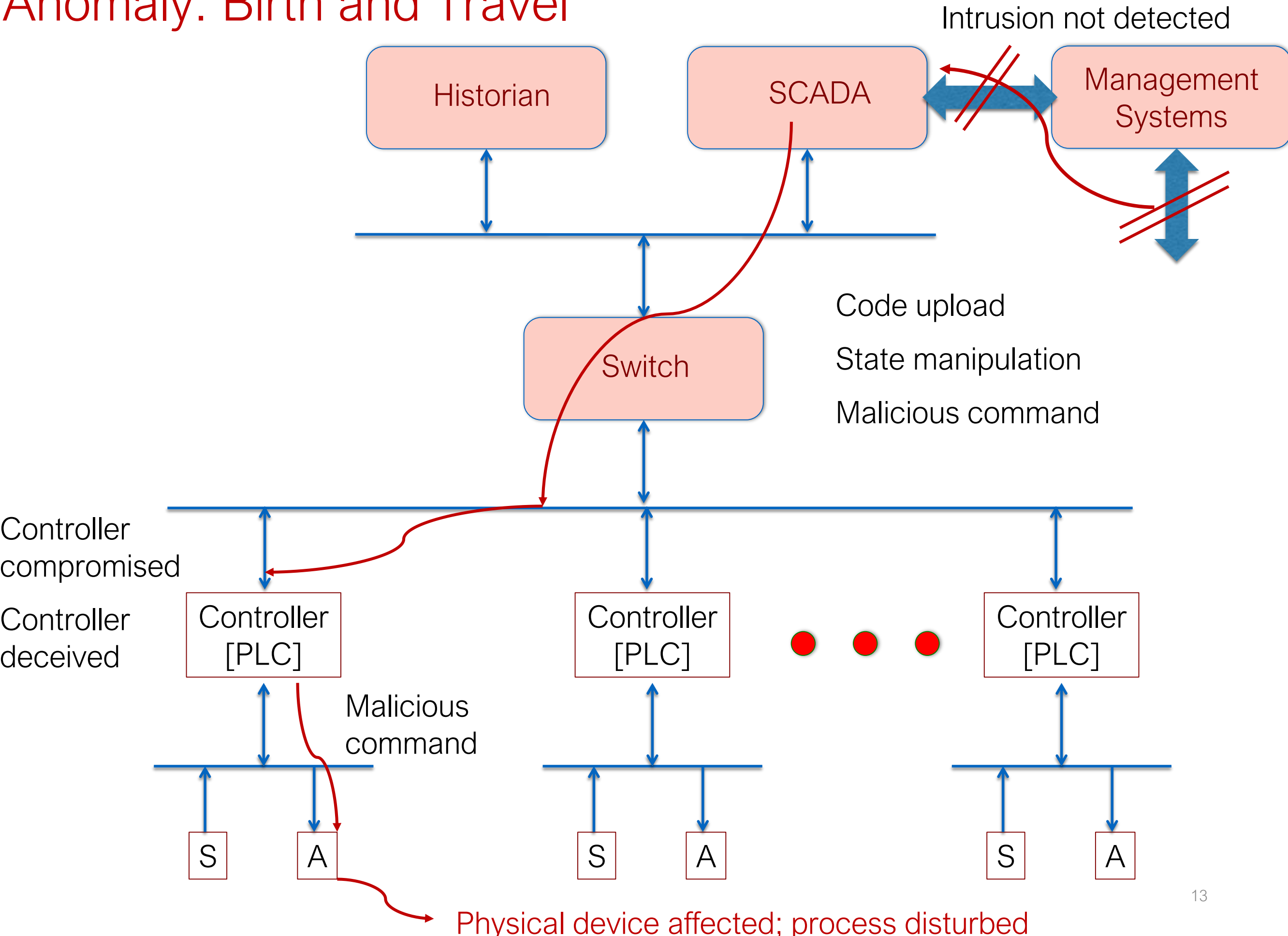
Thorough testing

Secure design

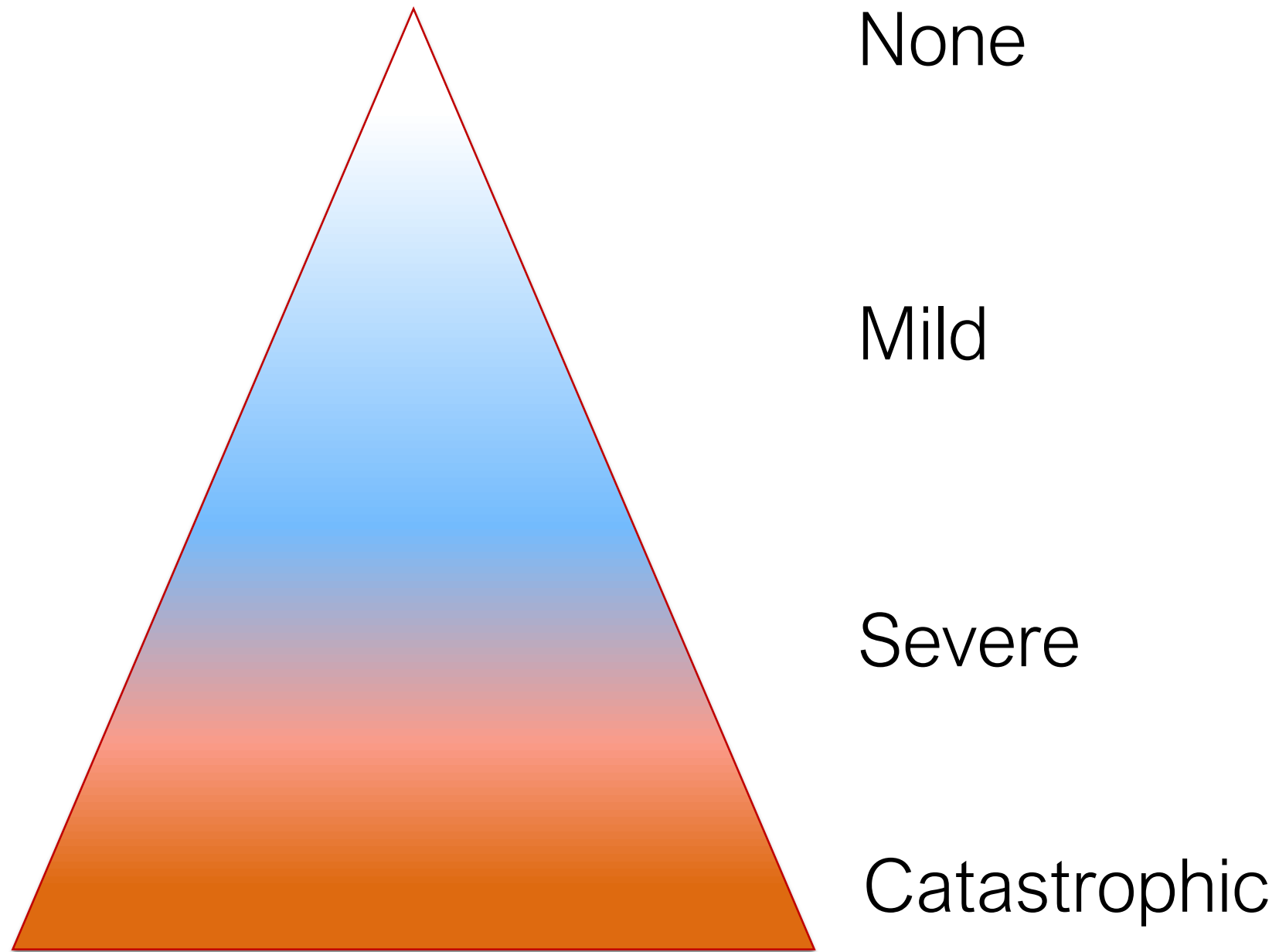
Firewalls

IDS

# Anomaly: Birth and Travel



# The Anomaly Impact Pyramid





## C. Detection

# Requirements

Ultra-high detection rate

- rare for an anomaly to be not detected

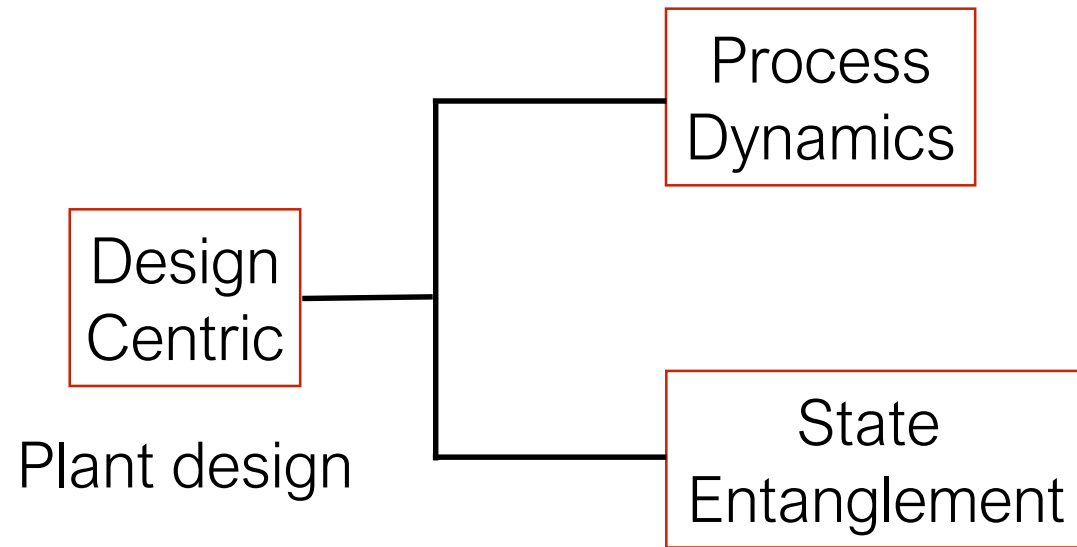
Ultra-low rate of false alarm:

- e.g., less than 1-false alarm in 6-months; data collected every second

Timely detection

- Offers “enough” time for an operator to take corrective action and avoid damage

# Approaches for Detection



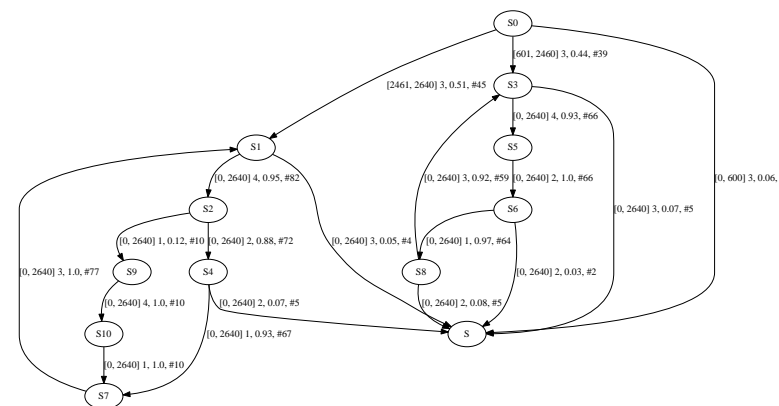
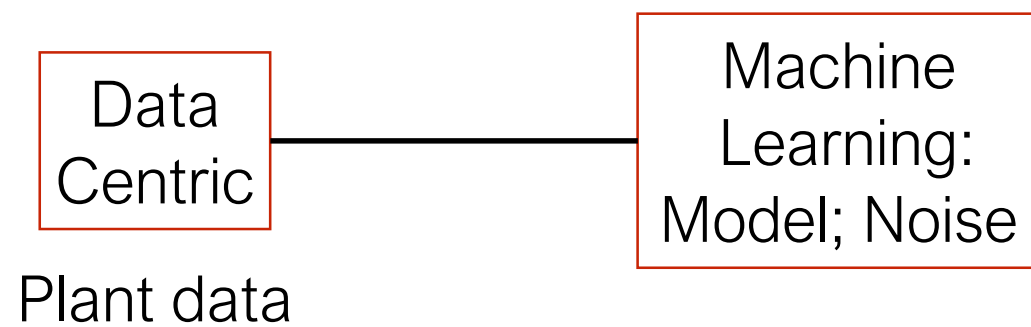
$$\dot{x} = f(x, u, \eta)$$

$$y = g(x, \theta)$$

Fabio et al. 2013

**if** (q(c) == v<sub>i</sub>)  
q(S);

Adepu et al. 2016



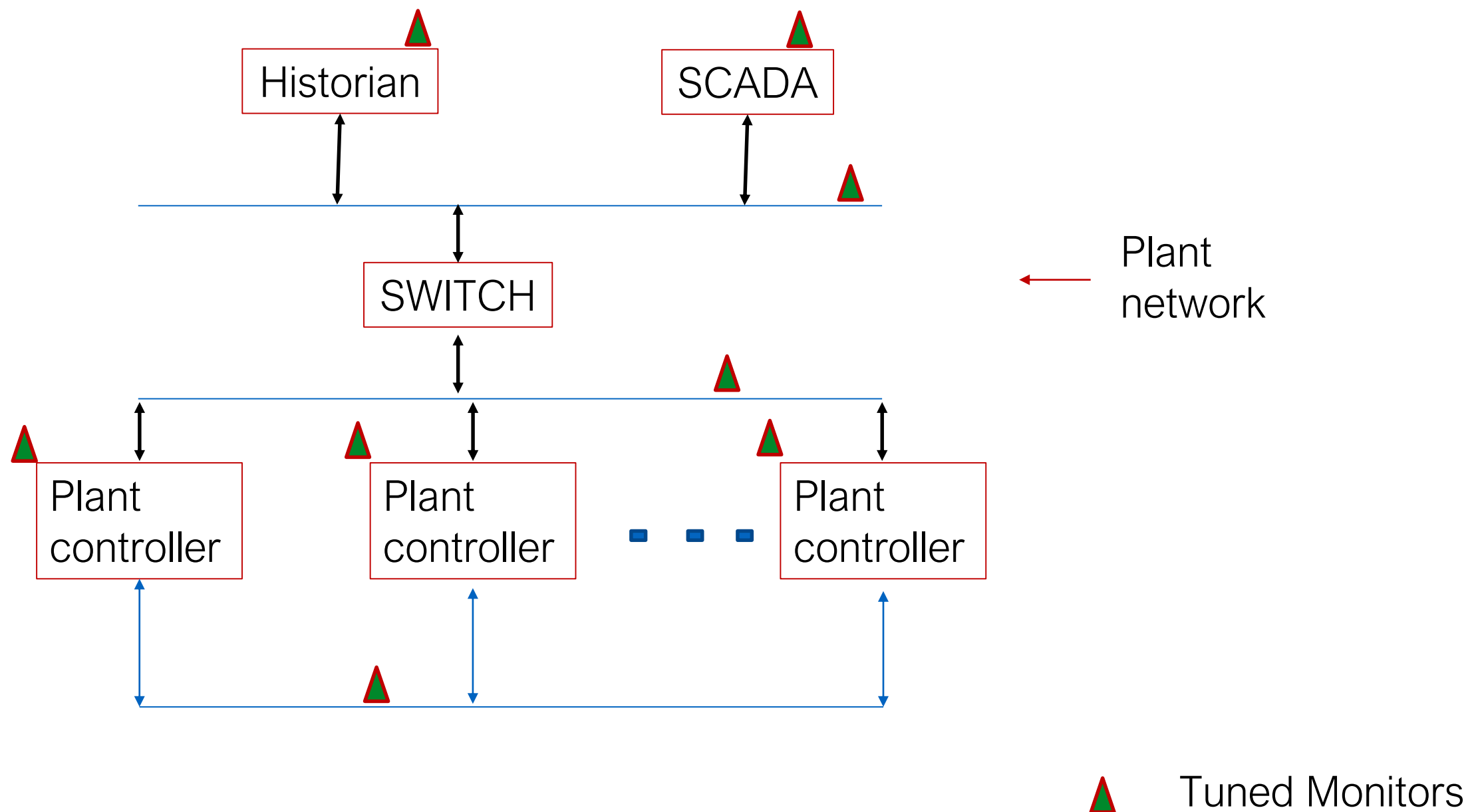
Qin et al. 2018  
Mujeeb et al. 2018

$$Y_k = f(Y_{k-1}, Z_1, Z_2, \dots, Z_n)$$

Heng et al. 2019

# DAD: Monitor placement

**Monitor:** A coded version of a set of rules that must hold during normal operation.



# Claim

Near perfect anomaly detection is achievable BUT... may not be adequate to protect a plant from severe damage.

## D. Command Validation



# Definitions

$\omega(t, a)$ : A **well-formed** command sent to actuator **a** at time **t**.

$\omega(t, a)$ : Valid iff  **$f(a, \omega, s_k)$** , where  $s_k$  is plant state when the command is issued.

$f(a, \omega, s_k)$ : actuator function for  $\omega(t, a)$  ;  
ensures correct and safe operation of the plant

# Sample Actuator Functions

<b>Actuator</b>	<b>Command Set</b>	<b>Actuator functions</b>
P101	{ON, OFF}	$f[P101 ON]({LIT101, LIT301, MV201}) = (LIT101 > 250 \text{ AND } LIT301 \leq 800 \text{ AND } MV201 == \text{OPEN})$ $f[P101 OFF]({LIT101, LIT301, MV201}) = (LIT101 < 250 \text{ OR } LIT301 > 800 \text{ OR } MV201 == \text{CLOSE})$
MV101	{OPEN, CLOSE}	$f[MV101 OPEN]({LIT101}) = LIT101 < 500$ $f[MV101 CLOSE]({LIT101}) = LIT101 > 80$

# Source of invalid (malicious) commands

Faulty component or network communications

Faulty network communications

Incorrect code

Cyber attack

# Origin of a Malicious Command

## Direct:

Attacker sends a malicious command to an actuator.

## Indirect:

Attacker deceives a PLC through manipulation of state variables.  
In turn the deceived PLC sends a malicious command.

# A Key Requirement for Validation

Given what we know about the origin of a command...

...a command validator must be able to obtain accurate estimate of the system state and predict continuous state variables.

# Challenge 1

How to ensure that a command validator can obtain accurate state estimate?



# Challenge 2

Where should a command validator be installed?

# Challenge 3

When a command is found to be malicious, should it be sent to the target actuator?

# Challenge 4

How to avoid the damaging impact of late detection?

# Past work

Stone et al., 2012

Improved modeling and validation of command sequences using a checkable sequence language

Mashima et al., 2016

An active command mediation approach for securing remote control interface of substations

Lin et al., 2016

Runtime semantic security analysis to detect and mitigate control-related attacks in power grids

Maimone et al., 2018

RP-check: An architecture for spaceflight command sequence validation

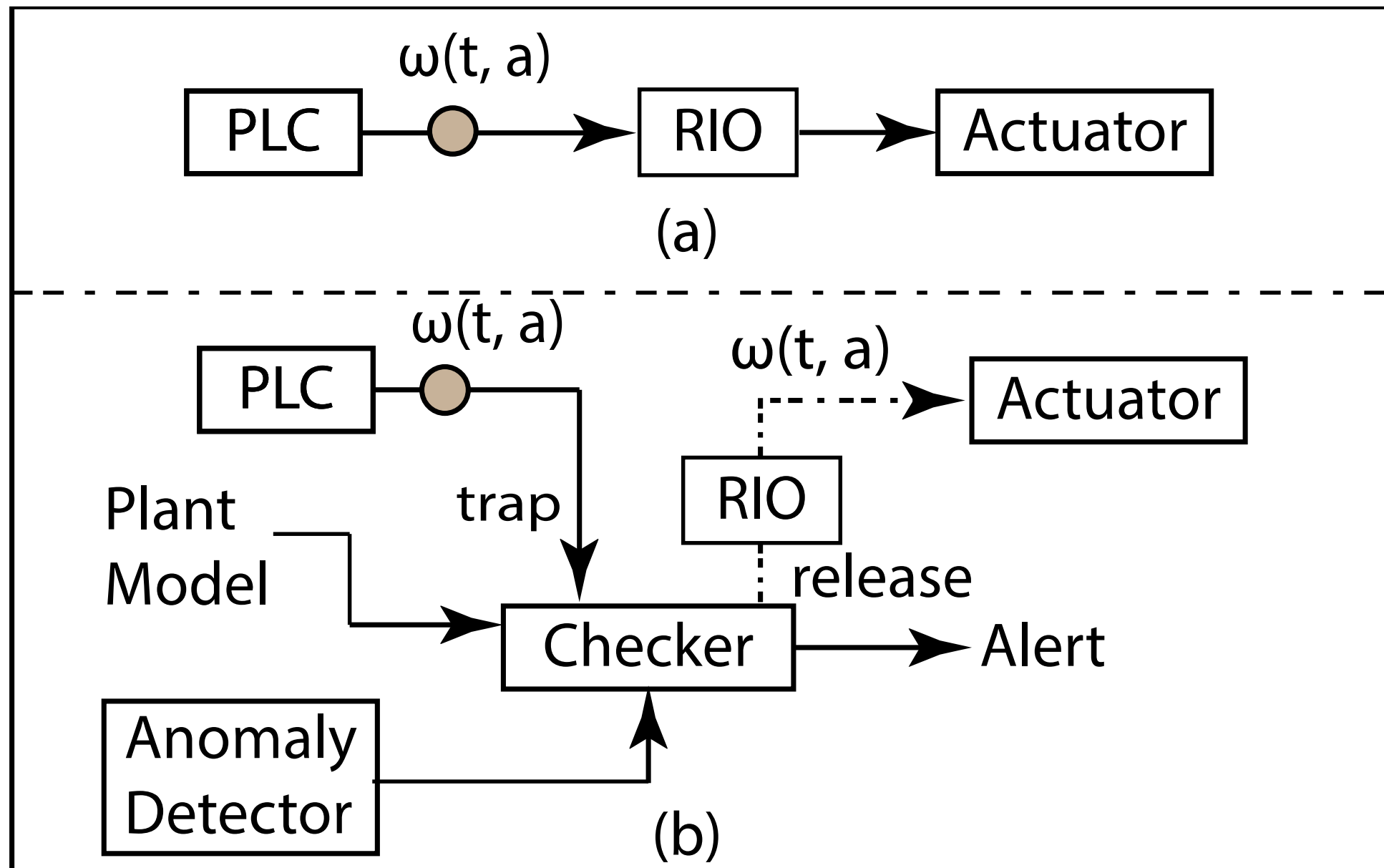
Our approach

Real-time (not simulation)

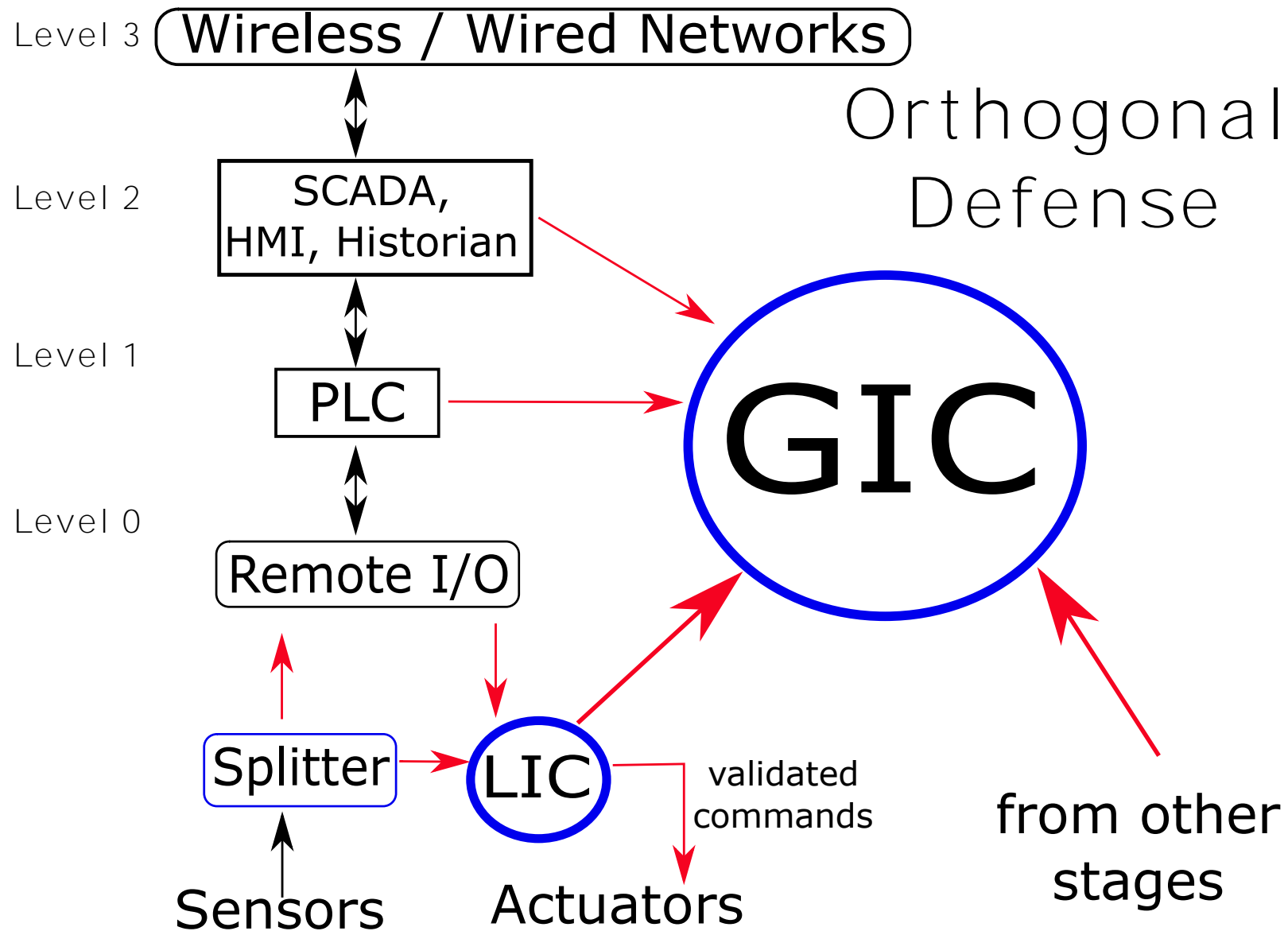
Design centric; partial state estimation

ALL commands are validated

# The Approach



# Architecture for Command Validation



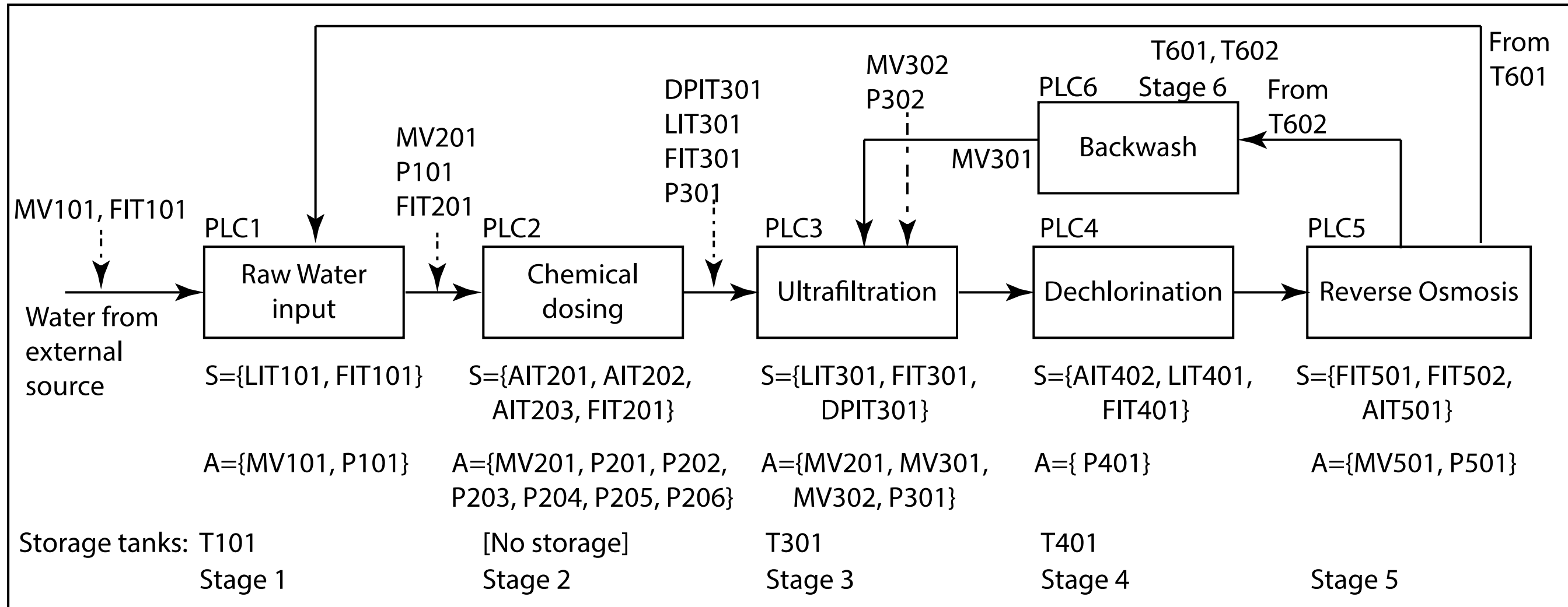
LIC: Local Intelligent Checker

GIC: Global Intelligent Checker

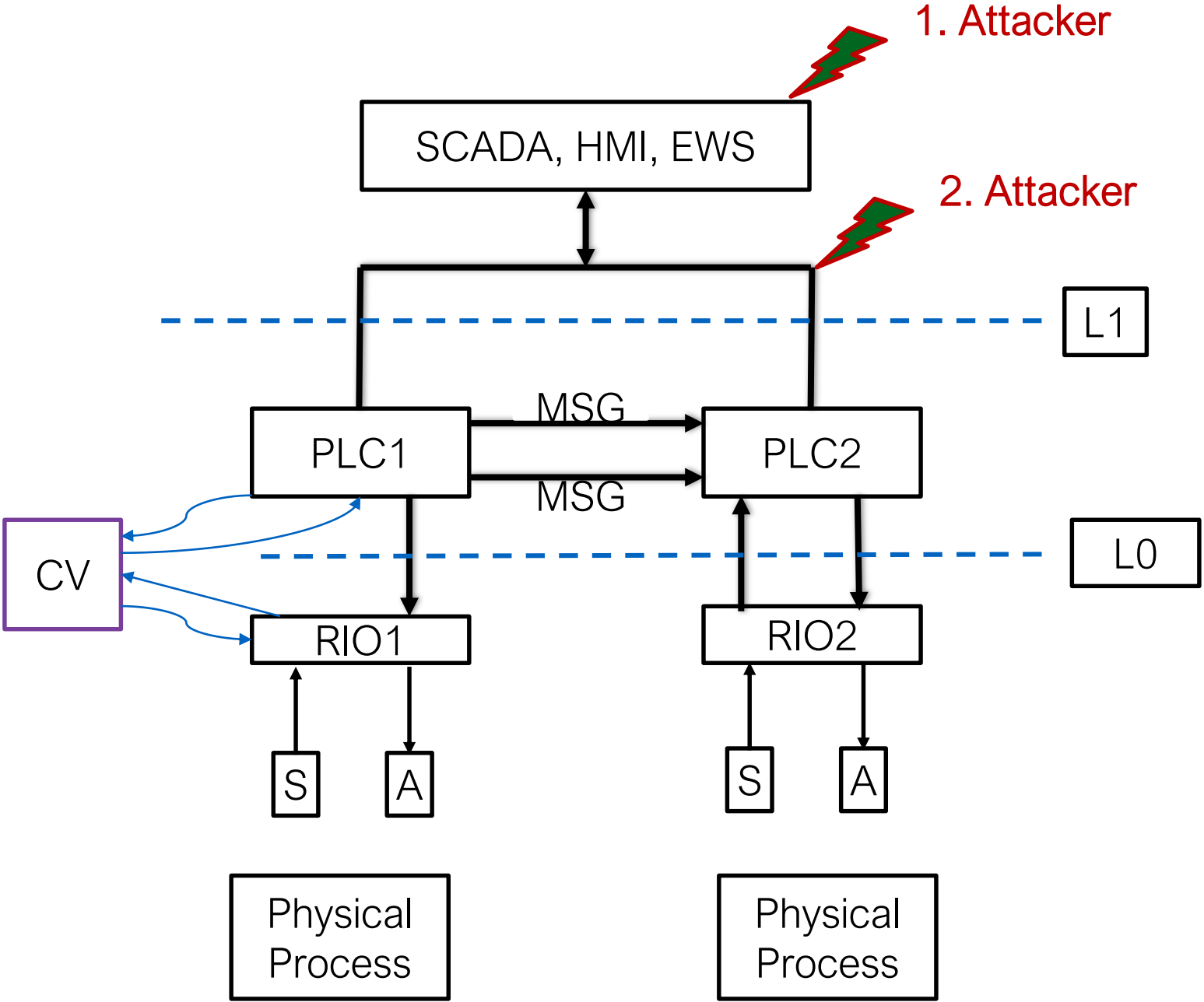


## E. Experimental Evaluation

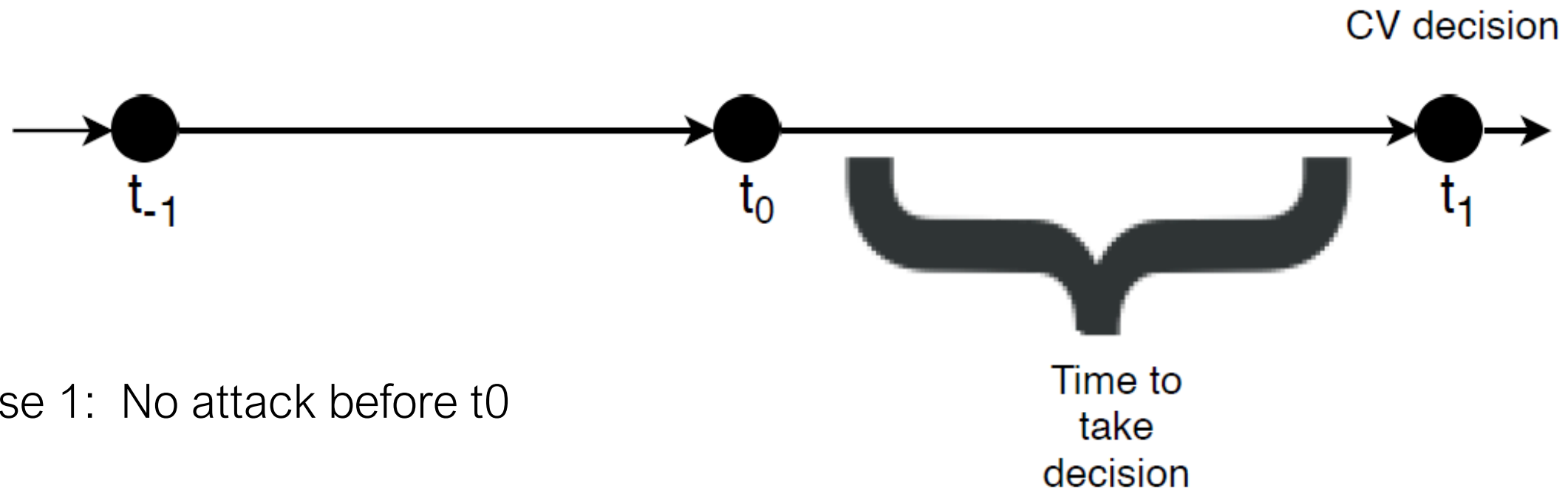
# Critical Infrastructure: Water Treatment



# Set-up



# Time to make decision



Case 1: No attack before  $t_0$

Case 2: Attack before  $t_0$ , detected before  $t_0$

**Case 3:** Attack before  $t_0$ ,

- a. detected between  $t_0$  and  $t_1$ ,
- b. detected after  $t_1$ , and
- c. Not detected.

# Attacks: Stage 1

Target	Attack	Detected first by
MV101	Open and Close (chatter attack)	CV
LIT101	Spoof level to low	DAD; then after 6-seconds CV stopped the MV101 open command
P101	Stop the pump	CV
LIT101	Cut sensor wire in RIO	DAD

## Attacks: Stage 2

Target	Attack	Detected first by
AIT202	Decrease the pH value	CV
MV201	Close	CV
P205 (NaOCl)	Stop the pump	CV
P201, P202	Turn ON	CV

# Attacks: Stage 3

Target	Attack	Detected first by
P301	Stop outflow from UF	CV
DPIT301	Activate backwash	CV
LIT301	Spoof to HH	DAD

# Summary 1: Detection and anomalies

CV detected 8 out of 11 attacks.

Remaining three attacks:

- on analog values,
- detected by DAD, i.e., caused anomalies, but
- did not lead to the desired impact.



## Summary 2: Timing

No attack detected before  $t_0$ .

Attacks detected between  $t_0$  and  $t_1$ :

Stage 1: Two out of four attacks detected before  $t_1$

Stage 2: All four attacks detected before  $t_1$

Stage 3: Two out of three detected before  $t_1$

# Conclusions

In the experiments conducted, CV worked well in concert with the anomaly detector.

Anomalies arising out of continuous state variables are detected by DAD. These may lead to malicious commands (indirect).

Direct malicious attacks possible only when intelligent checkers are compromised.

## F. Next Steps

# Full Implementation and Evaluation

Implement CV across the entire plant.

Design and launch single and multi-point masking attacks.

# CV Inside PLCs?

Should CV, with state prediction, be placed inside PLCs?

# Design of Command Validator for Power Grid

Will the approach work on a power grid?

Timing is critical

100% anomaly avoidance?

Is that a realizable dream?

# Thanks...

...to all those who are making it happen!

## PhD Students

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Thank You!